

VSEBINSKI PRISPEVKI SLING PARTNERJEV

Naziv SLING partnerja: Univerza v Ljubljani, Fakulteta za strojništvo

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Naslov prispevka SLO: Uporaba LLM-ov pri parametričnem 3D modeliranju

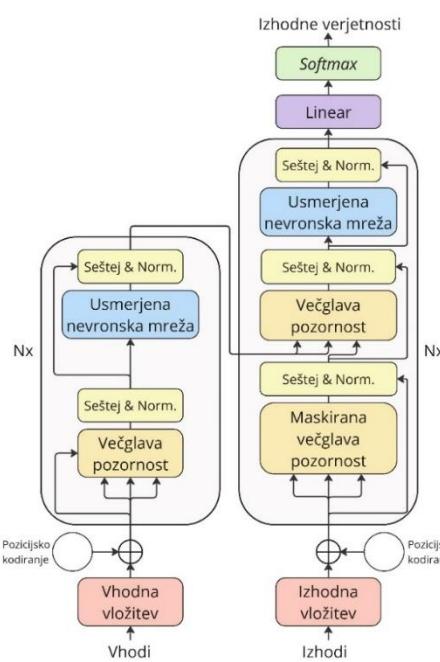
Naslov prispevka EN: Leveraging LLMs for parametric 3D modeling

Uporaba LLM pri parametričnem 3D modeliranju

Umetna Inteligenca (UI) je v zadnjih letih doživila hiter napredek, zlasti na področju generativnih in velikih jezikovnih modelov (LLM). Zaradi svoje zmogljivosti dobiva vedno večjo vlogo v različnih panogah, tudi v inženirstvu. Z namenom, da bi UI čim bolj efektivno vključili v strojniške procese, smo raziskali kako in kje lahko najbolje izkoristimo njene zmožnosti. V študiji predstavljamo metodologijo, ki UI vključuje v računalniško podprt modeliranje (CAD) ter omogoča preprosto in učinkovito pretvorbo besedilnega opisa v parametričen 3D model, zapisan v STEP formatu.

Teoretično ozadje:

UI kot jo poznamo danes, pogosto poimenujemo kar »moderna« UI. Poganjajo jo predvsem umetne nevronske mreže (NN) in globoko učenje (DL) [1], ki sta pojma, poznana že iz prejšnjega stoletja [1]. Za nedaven skokovit razvoj komercialnih AI asistentov in LLM, pa je zasluzen predvsem algoritem *Generative Pre-trained Transformer* (GPT), prvič predstavljen v članku *Attention Is All You Need* [2]. Shematski prikaz arhitekture transformerja je prikazan na sliki 1.

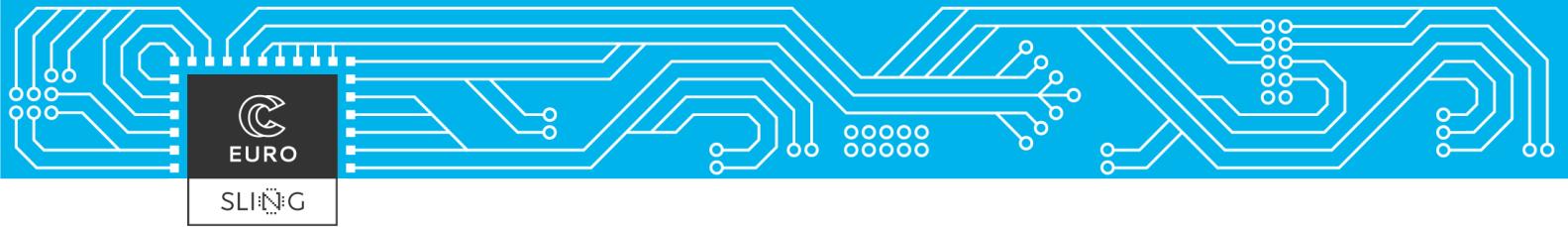


Slika 1: Shematski prikaz GPT tehnologije [2]



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EURO

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GPT modeli so UI revolucionizirali predvsem na področju procesiranja naravnega jezika (NLP) in s tem omogočili funkcionalnosti, ki nam pred tem niso bile na voljo. Sposobni so samonadzorovanega učenja [3], kar pomeni, da se lahko model uči tudi iz neoznačenih podatkov. Generiranje tekstovnih zapisov s pomočjo GPT modelov deluje tako, da na podlagi podanega konteksta model »napoveduje« besede, besedne zveze, znake ali črke. Ključni mehanizem, ki mu omogoča upoštevanje celotnega konteksta, se imenuje »pozornost«. Ta sposobnost modelu omogoča, da bolje razume dolga besedila in izboljša interpretacijo uporabniških vnosov [2]. Podoben pristop, kot se uporablja pri učenju in generiranju besedil, je mogoče uporabiti tudi za programske jezike. Komercialna orodja, kot je ChatGPT, so na ta način hitro osvojila znanje priljubljenih programskih jezikov. To smo prepoznali kot odlično izhodišče za nadaljnje raziskave ter to izkoristili za snovanje parametričnih 3D modelov.

Izbira ustreznih orodij

Na voljo je več komercialnih orodij, ki temeljijo na LLM tehnologiji. Trenutno najbolj izstopa podjetje OpenAI, ki je razvilo več zmogljivih modelov in jih ponuja uporabnikom preko platforme ChatGPT. Dostop do teh modelov ni omejen le na platformo, temveč je mogoč tudi preko aplikacijskega programskega vmesnika (API), kar je za nas odlična izbira. S tem lahko v nadaljevanju avtomatiziramo večji del naše metodologije. Trenutno je najzmogljivejši model, ki je dostopen prek API protokola, je GPT-4o model, za katerega smo se na koncu tudi odločili.

Zaradi priljubljenosti in široke uporabe programskega jezika *python* smo se odločili, da bo naš asistent temu ustrezno tudi prilagojen. Polet tega smo se odločili, da asistenta obogatimo z znanjem odprtakodne knjižnice *Open CASCADE* (OCC), oziroma z *python* »ovojsnikom« *pythonOCC-core*. Knjižnica OCC temelji na programskem jeziku C++ in omogoča različne funkcionalnosti, kot so 3D modeliranje, vizualizacija modelov, simulacije ter izvoz in uvoz različnih 3D formatov. Razvoj ovojsnika je spodbudilo predvsem dejstvo, da je C++ nizkonivojski programski jezik in zato za strojne inženirje precej zahteven za uporabo.

Metodologija dela

Naš cilj je razviti asistenta, ki bo sposoben generiranja strojniških 3D modelov z visoko stopnjo natančnosti in pravilnimi inženirskimi pristopi. Natančnost zagotavljamo tako, da modele generiramo s pomočjo *python* skripte, ki kot rezultat ustvari uporabno STEP datoteko. Večina obstoječih generativnih modelov, ki so sposobni ustvarjati 3D oblike, temeljijo na podlagi mrežnih 3D modelov, katerih uporabnost v inženirstvu je omejena zaradi pomanjkljive natančnosti in tehnične doslednosti. Kljub temu, da ima LLM, kot je GPT-4o, osnovno poznavanje knjižnice *pythonOCC-core*, je generiranje kompleksnih strojniških oblik zelo zahteven proces. Zanesljivost asistenta lahko izboljšamo z dodatnim uglaševanjem in naborom opornih skript, na katere se lahko opre pri generiranju 3D modelov.

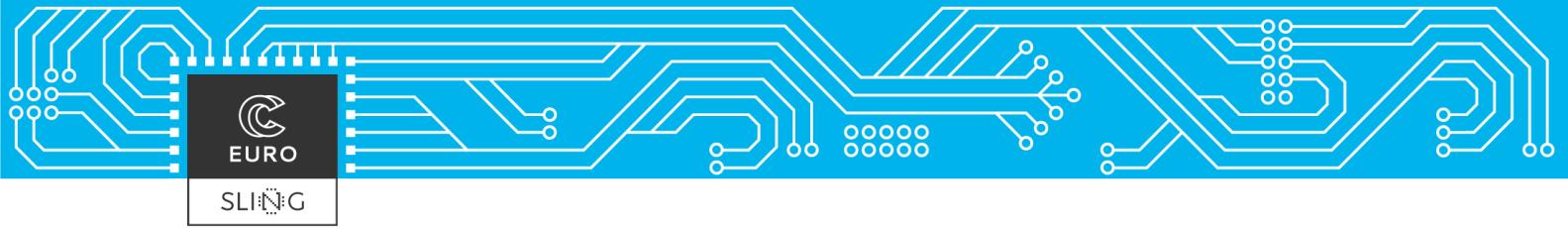
V tej študiji smo se osredotočili na ključne strojne elemente in omogočili kvalitetno generacijo le-teh. S pravilnim pristopom lahko asistenta opremimo z vsem potrebnim znanjem za generiranje poljubnih strojniških oblik. V okviru te študije smo se osredotočili predvsem na generiranje 3D modelov gredi, znanje asistenta pa želimo razširiti tudi na sledeče elemente:

- **Vzmeti**
- **Zobniki**
- **Standardni elementi (vijaki, ležaji, matici, podložke, vskočniki, mozniki,...)**

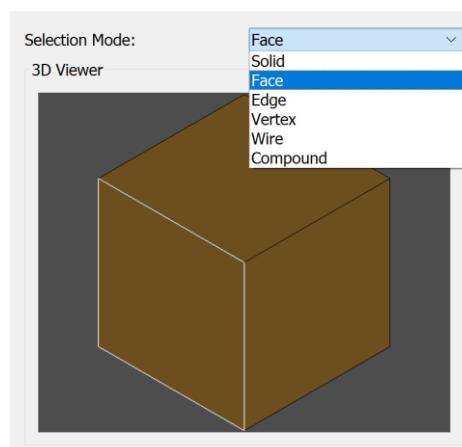
Za čim boljše rezultate smo asistenta opremili tudi s podporo za izvajanje manjših operacij, kot so izdelava utorov, oblikovanje iztekov za orodje ter dodajanje posnetij.

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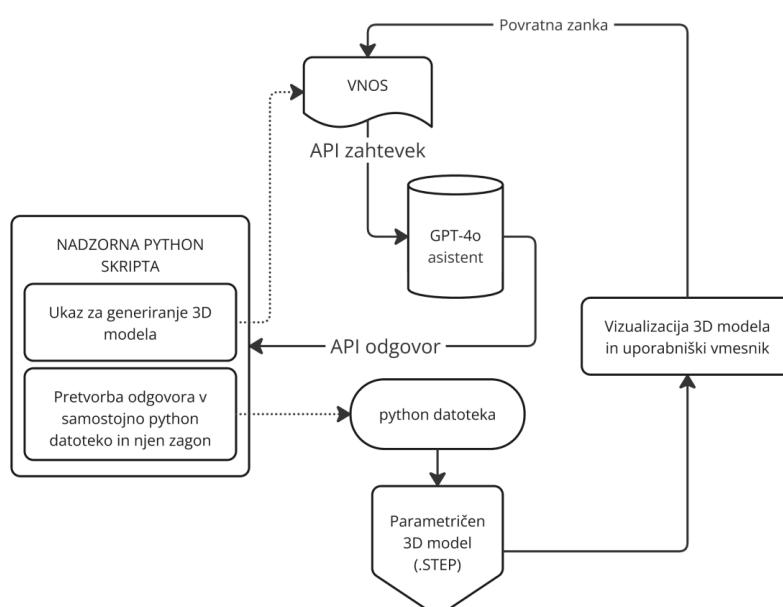


Pred vzpostavljivjo celotne API komunikacije smo najprej testirali rezultate LLM-a kar na platformi Chat-GPT, ki podobno kot API omogoča dostop do GPT-4o modela, vendar na bolj enostaven način. Med preizkušanjem smo ugotovili, da pri bolj kompleksnih 3D modelih, tekstovni vnesi postanejo zelo dolgi. Poleg tega je pogosto težko natančno opisati, na katerih robovih želimo dodati posnetja. Zato smo se odločili, da vzporedno z API komunikacijo vzpostavimo tudi vizualizacijo vmesnih rezultatov, kar nam omogoča boljši nadzor nad procesom generiranja. Poleg vizualizacije smo dodali tudi možnost izbire različnih topoloških elementov, kar omogoča uporabniku, da nekatere stvari določi neposredno na modelu. Vizualizacija vmesnega rezultata in izbiro topoloških elementov je prikazana na sliki 2, na preprostem primeru kocke.



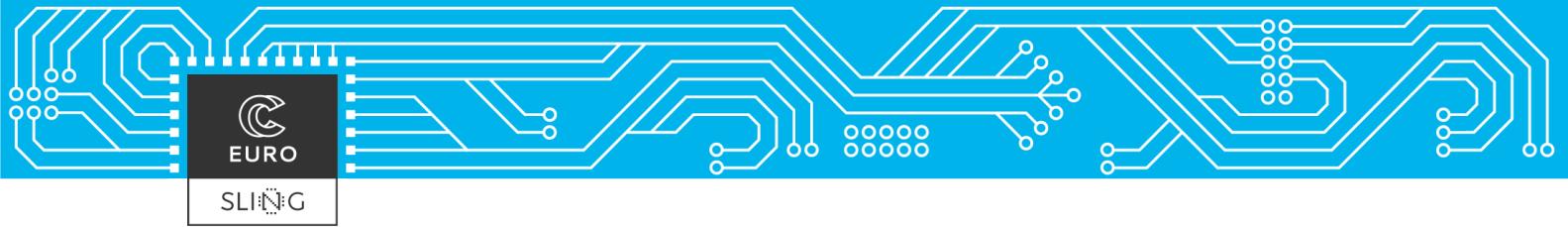
Slika 2: Izbiro topoloških elementov na enostavnem primeru kocke.

Z omogočeno izbiro topoloških elementov lahko uporabnik podaja natančnejša in podrobnejša navodila, hkrati pa se zmanjša potreba po detajlnem opisanju v samem besedilnem vnosu. Ena glavnih omejitev moderne UI je pomanjkanje inženirskega izkušenja in razumevanja inženirskega načela, zaradi česar še ni sposobna samostojno sprevzemati odločitev na tej ravni. Z razvitim vmesnikom želimo to težavo odpraviti. Inženir UI usmerja z jasno vizijo končnega izdelka, medtem ko mu UI pomaga s hitrejšo realizacijo in vizualizacijo njegovih zamisli. Celotna metodologija je prikazana v obliki diagrama na sliki 3.



Slika 3: Metodologija v obliki diagrama.



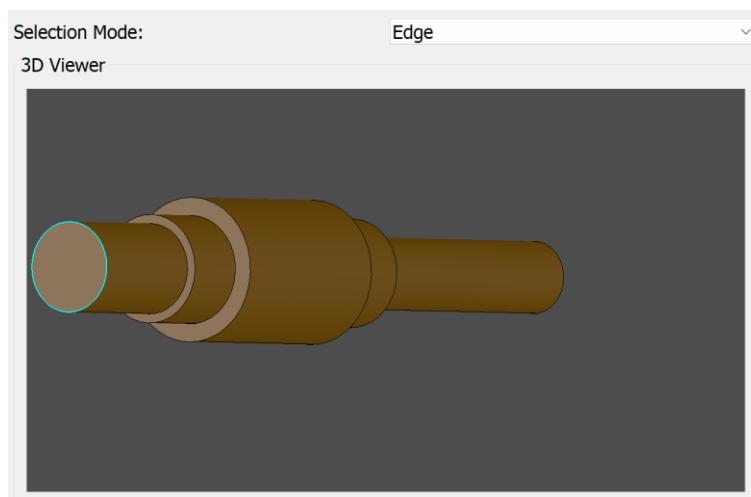


Dosedanji rezultati raziskave

Čeprav je raziskava še v teku, smo s predstavljenim tehnologijo že dosegli prve uporabne rezultate, ki jih aktivno izboljšujemo. Rezultate bomo predstavili v obliki uporabniških ukazov in 3D modela, ki jih generira AI asistent. Za prikaz bomo uporabili primer gredi.

Na sliki 4 je prikazana gred, ki jo je naš AI asistent ustvaril na podlagi naslednjega ukaza:

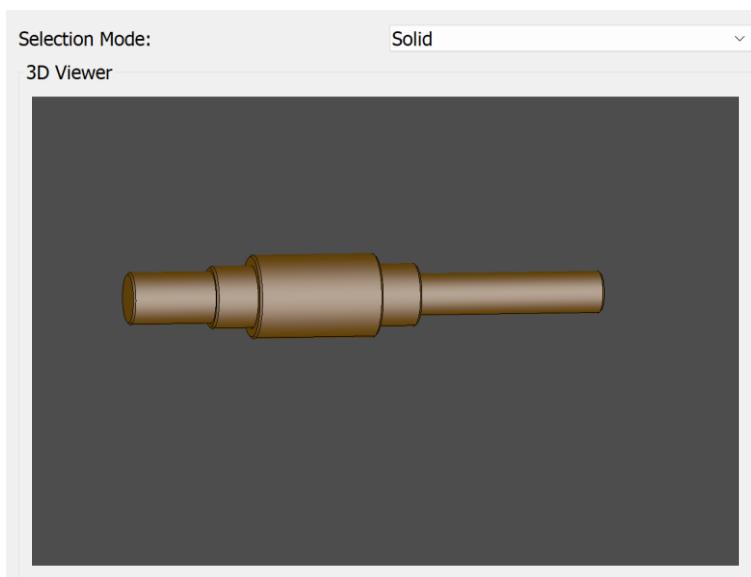
- **Ukaz:** Create a 230 mm long shaft. First segment has a diameter of 25 mm and it is 40 mm long. The next one has a diameter of 30 mm and is 20 mm long. Then a 40 mm diameter, which is 60 mm long. After that we have a 30 mm diameter which is 20 mm long, and the last one is 20 mm in diameter, and 90 mm long.



Slika 4: Rezultat 1 - 3D model gredi.

Prek uporabniškega vmesnika lahko uporabnik izbere ustrezen topološki element, na primer rob, in s tem natančno določi način izvedbe operacij, kot je posnetje (slika 5).

- **Ukaz:** On selected edges, create 1mm chamfers.

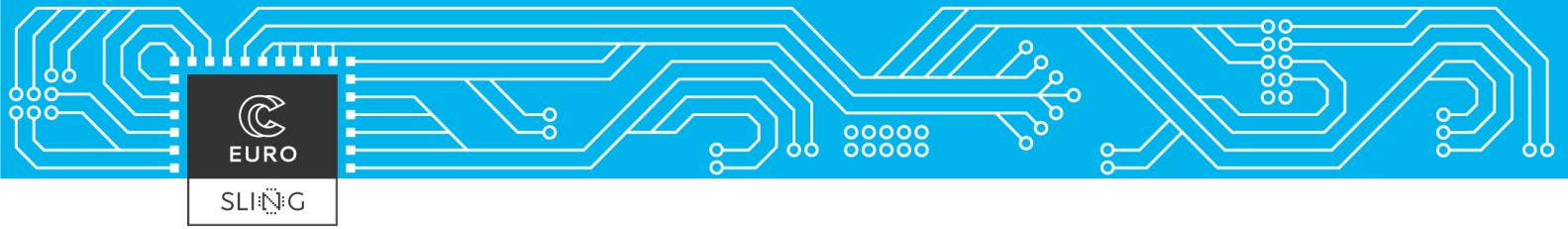


Slika 5: Rezultat 2 - 3D model gredi z dodanimi posnetji.



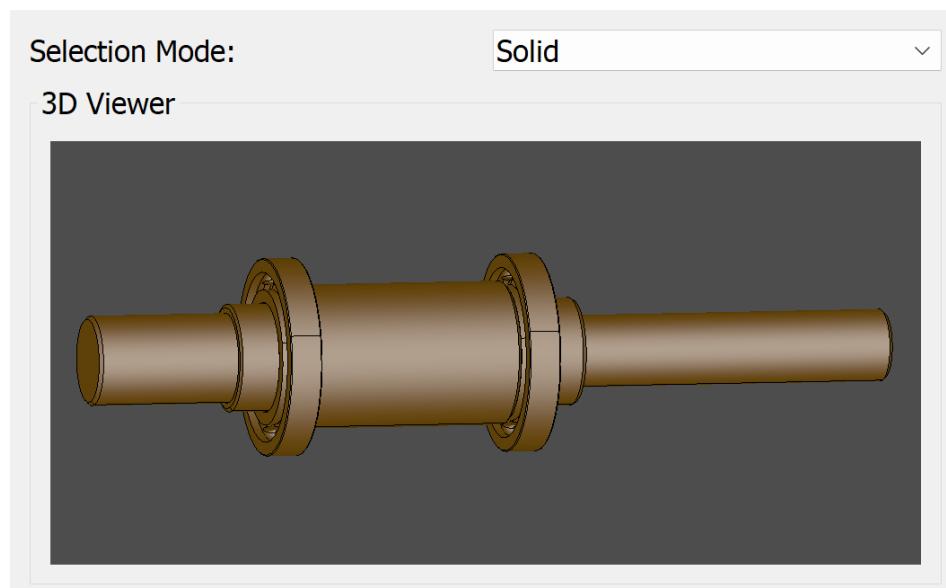
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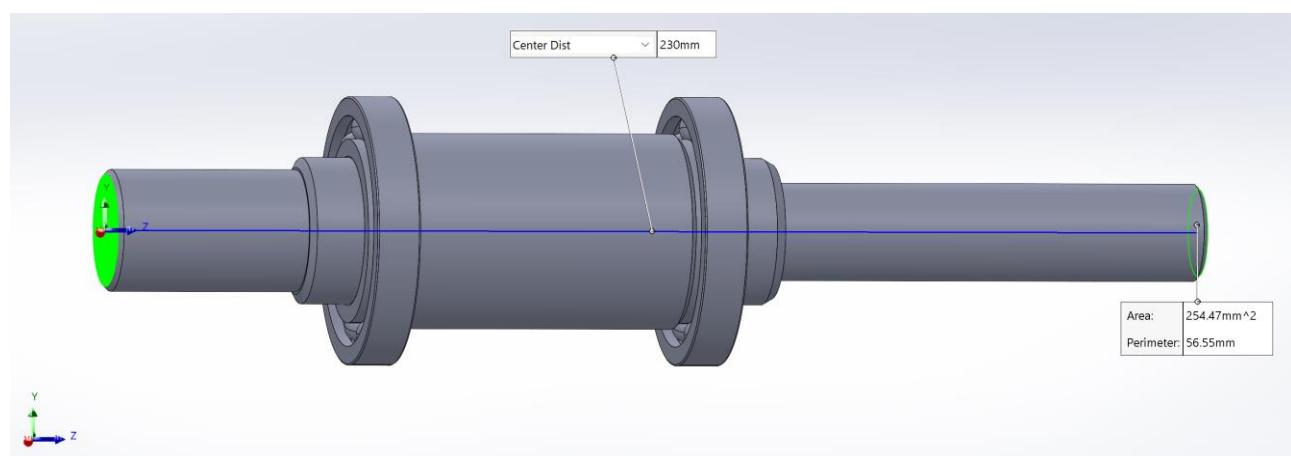
Predstavljeno metodologijo smo preizkusili tudi na primeru generiranja sestavov. Na gred smo želeli dodati dva krogljična ležaja (slika 6). Asistent ležajev ni generiral sam, temveč je do njih dostopal preko lokalno naložene STEP datoteke. Pozicijo ležajev na gredi smo mu določili s sledečim ukazom:

- **Ukaz:** Within the shaft script read the data/skf_bearing_16006.step file and assemble the shaft and two bearing files together. Position of the first bearing should be (0, 0, 55.5) and the position of the second one (0, 0, 124.5).



Slika 6: Rezultat 3 - 3D model gredi s posnetji, ter ustreznno pozicionirana kroglična ležaja.

Na sliki 7 je prikazan končni rezultat naše metodologije - gred s posnetji in dvema kroljičnima ležajema. Končno STEP datoteko lahko vizualiziramo z lastnim uporabniškim vmesnikom (slika 4, 5 in 6), hkrati pa smo jo preizkusili tudi v komercialni CAD programski opremi SolidWorks (slika 7). Preverili smo tudi celotno dolžino gredi, ki se ujema z začetnim ukazom (skupna dolžina 230 mm).

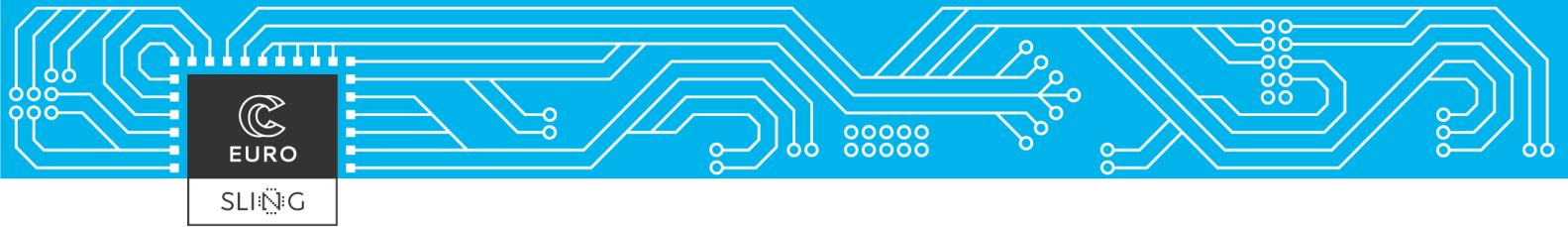


Slika 7: Rezultat 3: Prikaz v CAD okolju SolidWorks, ter pripadajoča gabarita v Z-osi.



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Zaključki

Razvojni proces in doseženi rezultati vodijo do naslednjih spoznanj:

- Z uporabo »večstopenjske« API komunikacije in LLM asistenta smo razvili metodo, ki omogoča ustvarjanje parametričnih 3D oblik že z osnovnim poznavanjem CAD modeliranja;
- Metoda generira veljavno STEP datoteko, kar olajša njeni integraciji v nadaljnje inženirske procese.
- Pomembno je paziti na halucinacije LLM asistenta, ki se pojavijo, kadar mu dajemo ukaze, ki presegajo njegovo področje znanja. V takšnih primerih si lahko asistent izmisli določene podatke, kar vodi do napačnih rezultatov.
- Z ugleševanjem asistenta, uporabo opornih skript in podajanjem dodatnih navodil lahko zanesljivost močno izboljšamo.
- Vizualizacija in uporabniški vmesnik omogoča inženirju preverjanje in izboljšanje 3D modela skozi vsako iteracijo.

ZAHVALA

Aktivnosti se izvajajo v okviru projekta GREENTECH, ki ga sofinancira Evropska unija – NextGenerationEU.

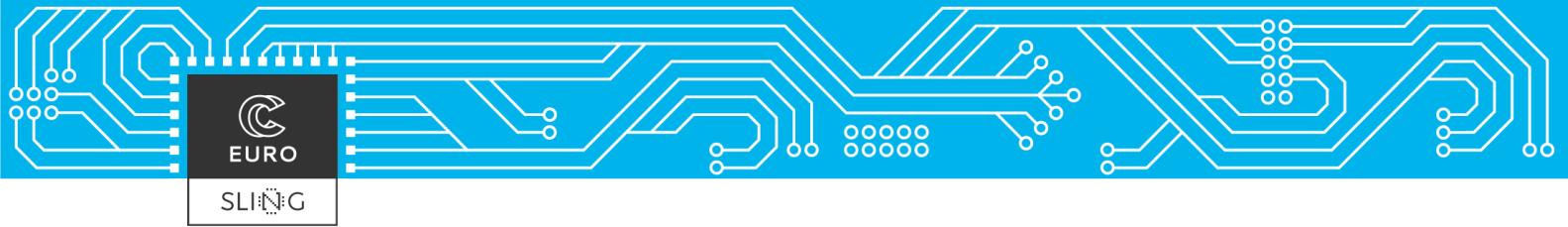
Viri:

- [1] J. Schmidhuber, *Annotated History of Modern AI and Deep Learning*, Technical Report IDSIA-22-22 (v2), IDSIA, 12/29/2022
- [2] A. Vaswani et al. *Neural Inf. Process. Syst.* **31** (2017) 6000-6010
- [3] OpenAI. *Improving Language Understanding by Generative Pre-Training*, [language_understanding_paper.pdf](https://cdn.openai.com/research/improving-language-understanding-by-generative-pre-training.pdf) (25.11.2024).



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Leveraging LLMs for Parametric 3D Modeling

Artificial Intelligence (AI) has made rapid progress in recent years, especially in the field of generative and large language models (LLMs). Its growing capabilities are making it increasingly important across various industries, including engineering. To integrate AI into mechanical engineering more effectively, we explored how and where its potential can be best utilized. This study presents a methodology that incorporates AI into computer-aided design (CAD), enabling a simple and efficient conversion of text descriptions into parametric 3D models written in the STEP format.

Theoretical Background

AI, as we know it today, is often referred to as "modern" AI. It is primarily powered by artificial neural networks (NNs) and deep learning (DL), concepts that have been known since the previous century [1]. The recent rapid development of commercial AI assistants and LLMs is largely driven by a new algorithm called Generative Pre-trained Transformer (GPT), which was first introduced in the paper *Attention Is All You Need* [2]. A schematic representation of the Transformer architecture is shown in Figure 1.

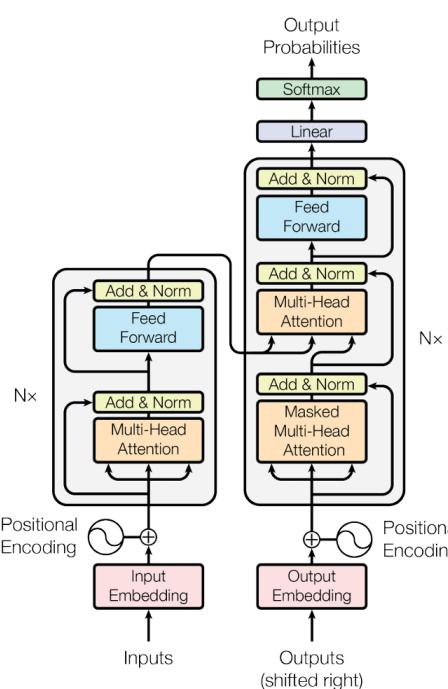


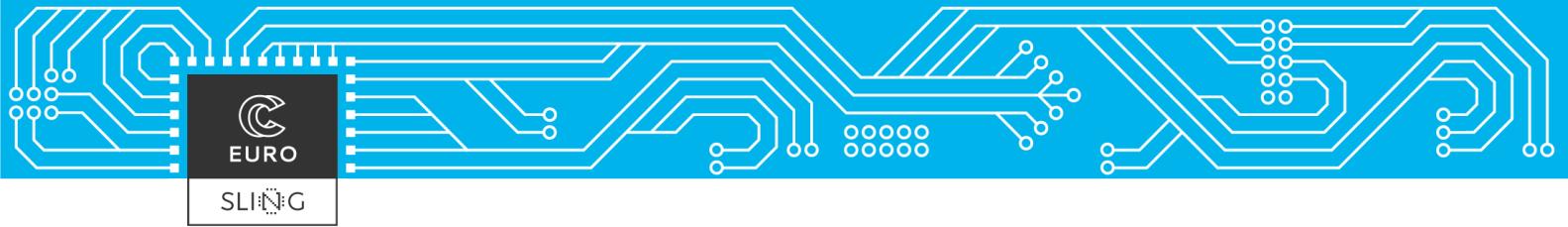
Figure 8: Schematic representation of GPT technology [2]

GPT models have revolutionized AI, particularly in natural language processing (NLP), enabling functionalities that were previously unavailable. They are capable of self-supervised learning [3], meaning they can learn from unlabeled data. Text generation using GPT models works by predicting words, phrases, characters, or symbols based on the given context. The key mechanism that allows the model to consider the entire context is called "attention." This capability helps the model better understand long texts and improve its interpretation of user inputs [2]. A similar approach used for learning and generating text can also be applied to programming languages. Commercial tools like ChatGPT have quickly acquired knowledge of popular programming languages this way. We recognized this as a great foundation for further research and leveraged it for developing parametric 3D models.



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Choosing the Right Tools

Several commercial tools based on LLM technology are available. The most notable among them is OpenAI, which has developed multiple powerful models and offers them to users through the ChatGPT platform. Access to these models is not only limited to the platform but is also available via an Application Programming Interface (API), making it an excellent choice for our needs. This allows us to automate a significant part of our methodology. Currently, the most powerful model accessible via API is the GPT-4o model, which we selected for our project.

Given the popularity and widespread use of Python, we decided to tailor our AI assistant to this programming language. Additionally, we enhanced the assistant's capabilities by integrating Open CASCADE (OCC), an open-source library, through its Python wrapper, pythonOCC-core. The OCC library, originally developed in C++, provides functionalities such as 3D modelling, model visualization, simulations, import/export of various 3D formats. The development of the Python wrapper was primarily driven by the fact that C++ is a low-level programming language, which makes it a bit more challenging for mechanical engineers. By utilizing pythonOCC-core, we can harness the power of OCC in a more accessible and user-friendly way.

Methodology

Our goal is to develop an AI assistant capable of generating engineering 3D models with high precision and correct mechanical design principles. To ensure accuracy, we generate models using Python scripts, which output STEP files that can be seamlessly integrated into engineering workflows. Commercial generative 3D models are mostly based on mesh representations, which lack the precision and technical consistency required for engineering applications. While LLMs like GPT-4o have basic knowledge of the pythonOCC-core library, generating complex mechanical components remains a challenging task. To improve reliability, we enhance the assistant with fine-tuning and a set of reference scripts that serve as a foundation for 3D model generation.

For this study, we focused on generating key mechanical components to ensure high-quality output. With the right approach, we can equip the assistant with all the necessary knowledge to generate various engineering shapes.

In this study, we primarily focused on shaft generation, but we aim to expand the assistant's capabilities to include:

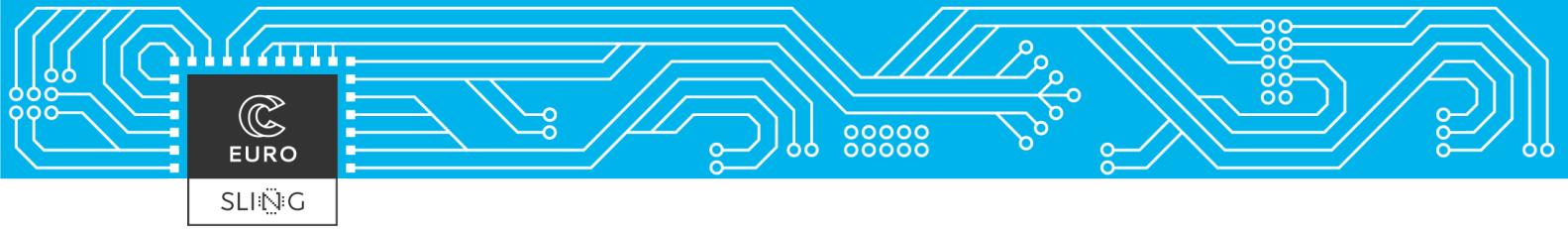
- Springs
- Gears
- Standard mechanical elements (bolts, bearings, nuts, washers, pins, etc.)

To achieve high-quality results, we also enabled the assistant to perform minor operations, such as creating grooves and adding chamfers or fillets. Before establishing full API communication, we initially tested LLM-generated results directly on the ChatGPT platform, which, like the API, provides access to the GPT-4o model, but in a more user-friendly way. During testing, we discovered that for complex 3D models, text inputs become lengthy and that it is often difficult to specify exactly where features like chamfers should be applied. To address this, we implemented real-time visualization of results alongside API communication, allowing better control over the generation process. Additionally, we introduced a topological element selection feature, enabling users to define certain details directly on the 3D representation.



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A simple example of visualization and topological element selection is shown in Figure 2, using a basic cube model.

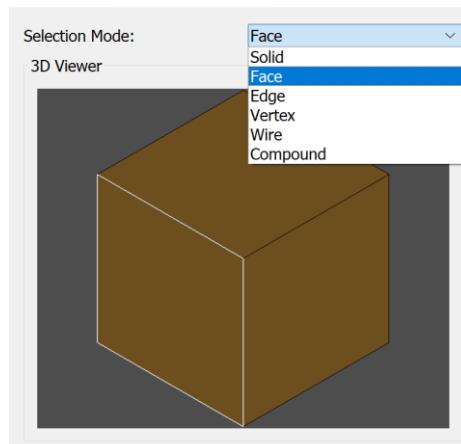
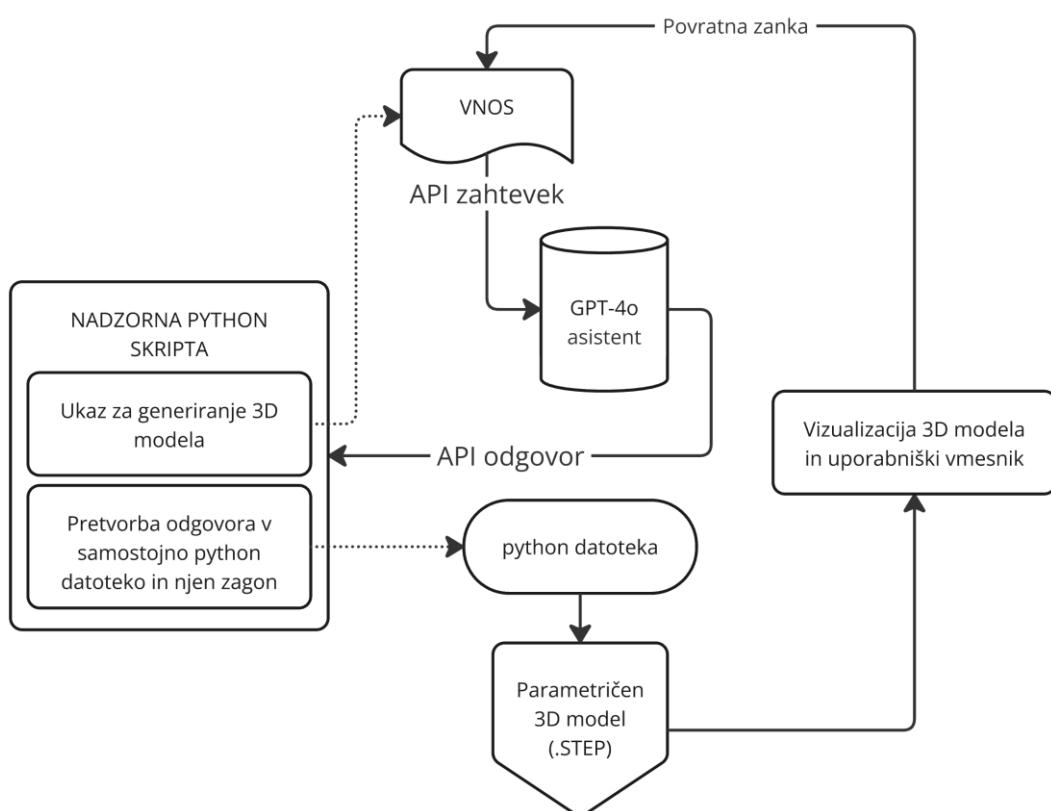


Figure 9: Selection of topological elements on a simple cube example.

With the ability to select topological elements, the user can provide more precise and detailed instructions while reducing the need for highly detailed textual input. One of the main limitations of modern AI is its lack of engineering experience and understanding of mechanical design principles, which prevents it from making fully autonomous decisions at this level. The developed interface aims to overcome this challenge. The engineer guides the AI with a clear vision of the final product, while the AI assists by accelerating the realization and visualization of ideas. The complete methodology is presented in the diagram in Figure 3.

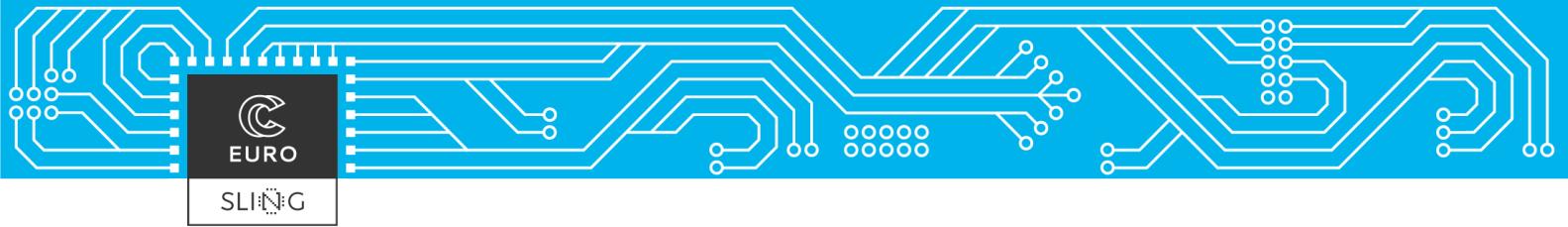


Slika 10: Diagram representation of the Methodology.



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Current Research Findings

Although the research is still ongoing, the presented technology has already produced the first useful results, which we are actively improving. The results will be presented in the form of user prompts and the 3D models generated by the AI assistant. For demonstration purposes, we will use the example of a shaft. Figure 4 shows the shaft created by our AI assistant based on the following prompt:

- *Prompt: Create a 230 mm long shaft. First segment has a diameter of 25 mm and it is 40 mm long. The next one has a diameter of 30 mm and is 20 mm long. Then a 40 mm diameter, which is 60 mm long. After that we have a 30 mm diameter which is 20 mm long, and the last one is 20 mm in diameter, and 90 mm long.*

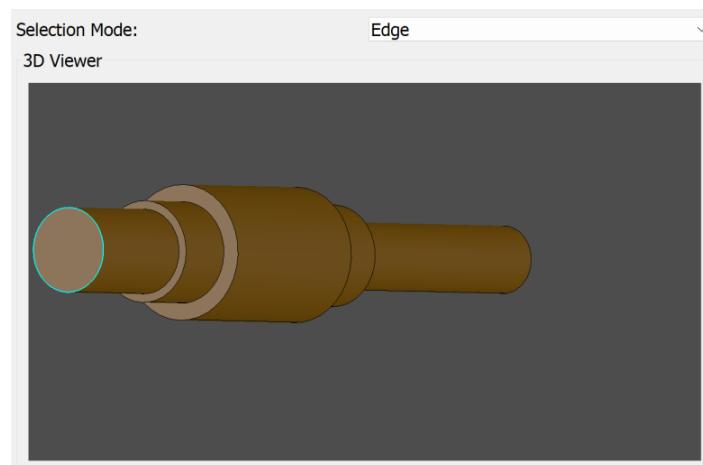


Figure 11: Result 1 – 3D model of a shaft.

Through the user interface, the user can select the appropriate topological element, such as an edge, and precisely define how operations like chamfering should be performed (Figure 5).

- *Prompt: On selected edges, create 1mm chamfers.*

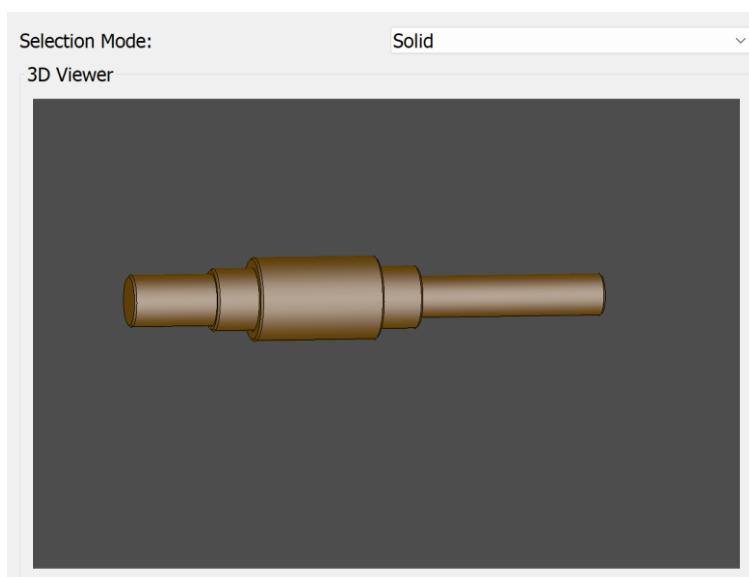
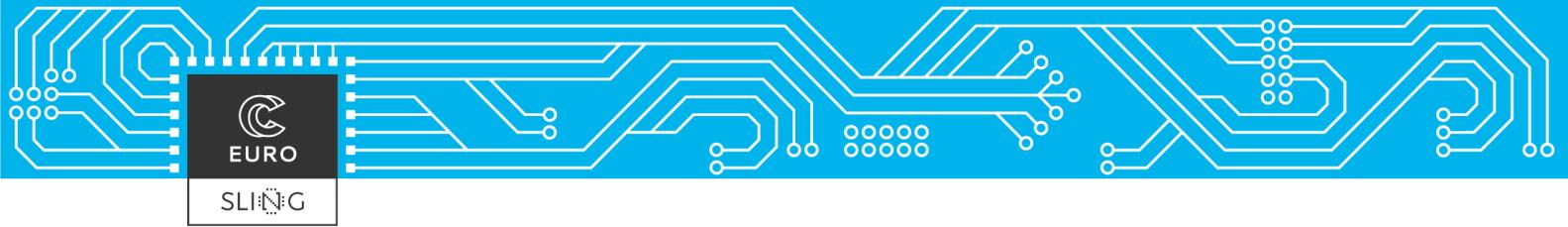


Figure 12: Result 2 - 3D model of a shaft with chamfers.



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We also tested the presented methodology on the generation of assemblies. In this case, we aimed to add two ball bearings to the shaft (Figure 6). The assistant did not generate the bearings itself but accessed them through a locally stored STEP file. The position of the bearings on the shaft was defined using the following prompt:

- **Prompt:** Within the shaft script read the data/skf_bearing_16006.step file and assemble the shaft and two bearing files together. Position of the first bearing should be (0, 0, 55.5) and the position of the second one (0, 0, 124.5).

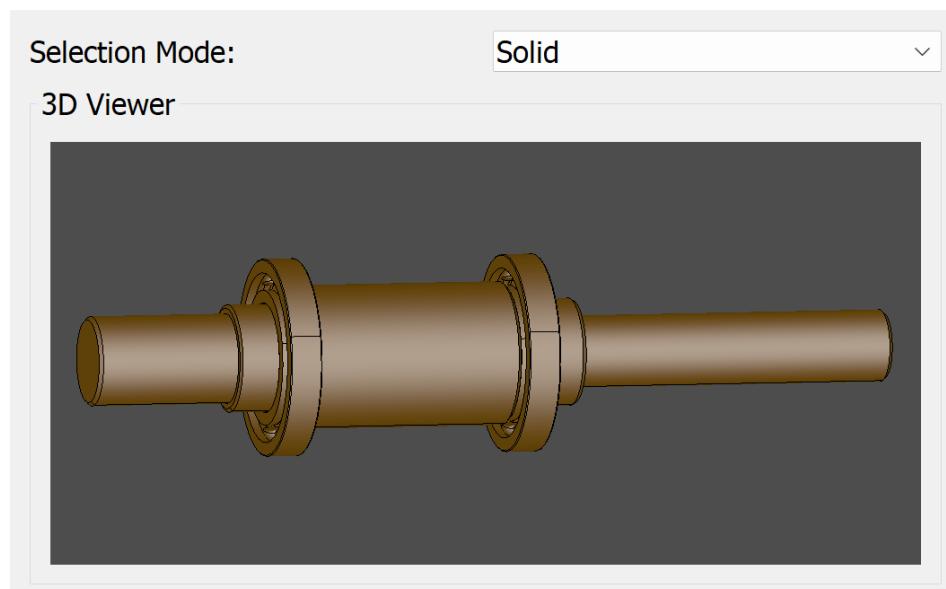


Figure 13: Result 3 - 3D model of a shaft with chamfers and ball bearings.

Figure 7 shows the result of our methodology – a shaft with chamfers and two ball bearings. The final STEP file can be visualized using our custom user interface (Figures 4, 5, and 6), but we also tested its compatibility with commercial CAD software, SolidWorks (Figure 7).

Additionally, we verified the total length of the shaft, which matches the initial command (total length: 230 mm).

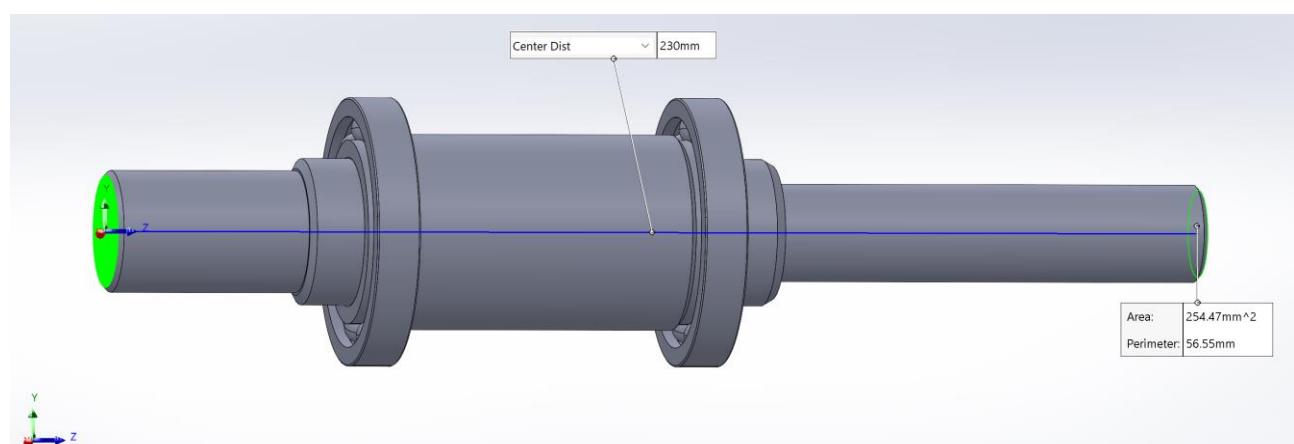
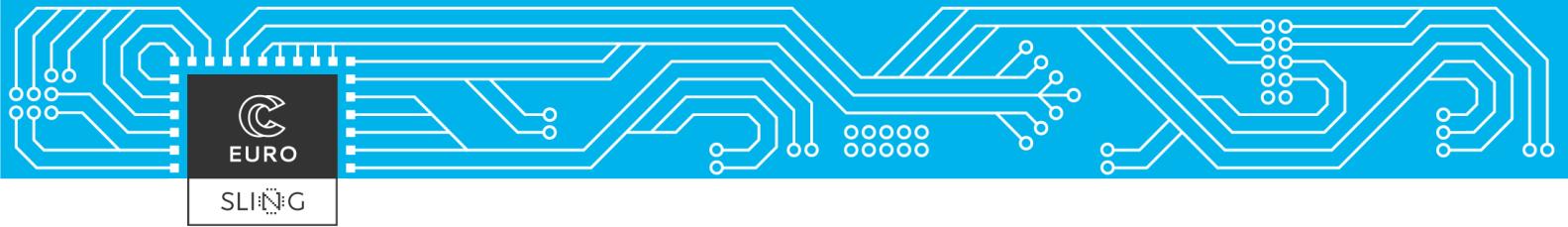


Figure 14: Result 3: Visualization in CAD environment (SolidWorks) and corresponding dimension along the Z axis.



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Conclusions

The development process and achieved results have led us to the following conclusions:

- By using multi-stage API communication with an LLM assistant, we developed a method that enables the creation of parametric 3D shapes with only basic knowledge of CAD modeling.
- The method generates a valid STEP file, making it easier to integrate into engineering workflows.
- It is important to be aware of LLM hallucinations, which occur when prompts exceed the model's knowledge. In such cases, the assistant may generate incorrect or fabricated data, leading to inaccurate results.
- Fine-tuning the assistant, using reference scripts, and providing additional instructions can significantly improve its reliability.
- Visualization and the user interface allow engineers to review and refine the 3D model throughout each iteration.

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